

Scalable preference disaggregation: A multiple criteria sorting approach based on the MapReduce framework

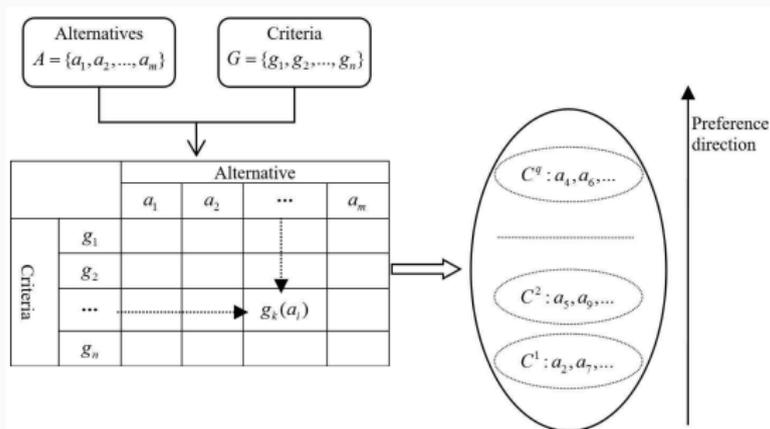
Jiapeng Liu

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School of Management
Xi'an Jiaotong University
P.R. China

Introduction

- Multiple criteria sorting (MCS) is the practice of assigning a set of alternatives evaluated on multiple criteria to predefined and preference-ordered categories.



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- Many approaches have been proposed to deal with MCS problems based on this indirect preference information.
 - methods motivated by value functions, such as the UTADIS method and its variants, and the MHDIS method
 - methods based on outranking relations, such as the ELECTRI Tri-B methods, ELECTRI Tri-C methods, ELECTRI-based methods, and PROMETHEE-based methods
 - rule induction-oriented procedures, such as the DRSA method and its extensions
 - techniques incorporating the weighted Euclidean distance

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 - Traditional decision problems usually involve several dozens of alternatives.
 - These methods require the data to fit into the main memory, in which LP/IP solvers search for the optimal solution.
 - This exceeds the processing capabilities of existing MCS methods in terms of the memory consumption and/or the computational time when dealing with huge amounts of data.

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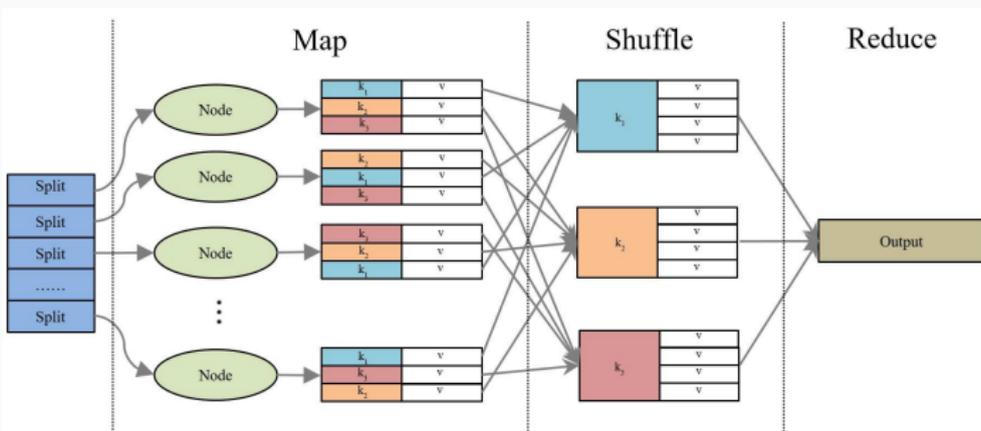
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- In this study, we propose a new approach based on the MapReduce framework, in order to address the MCS problem with a large set of alternatives and massive preference information.
- MapReduce is a popular parallel computing paradigm developed by Google Inc., which is designed to process large-scale data sets.



The proposed approach

- The aim of this study is to classify a finite set of m alternatives $A = \{a_1, a_2, \dots, a_m\}$ into p categories $\overline{C} = \{C_1, C_2, \dots, C_p\}$, such that C_{h+1} is preferred to C_h (denoted by $C_{h+1} \succ C_h$), $h = 1, \dots, p - 1$.

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- An assignment example specifies the assignment of a reference alternative $a^* \in A^R$ to a category $C(a^*) \in \overline{C}$.
- All the alternatives $a \in A \cup A^R$ are evaluated in terms of n criteria g_1, g_2, \dots, g_n .
- The performance of $a \in A \cup A^R$ on g_j , $j \in G = \{1, \dots, n\}$, is denoted by $g_j(a)$.

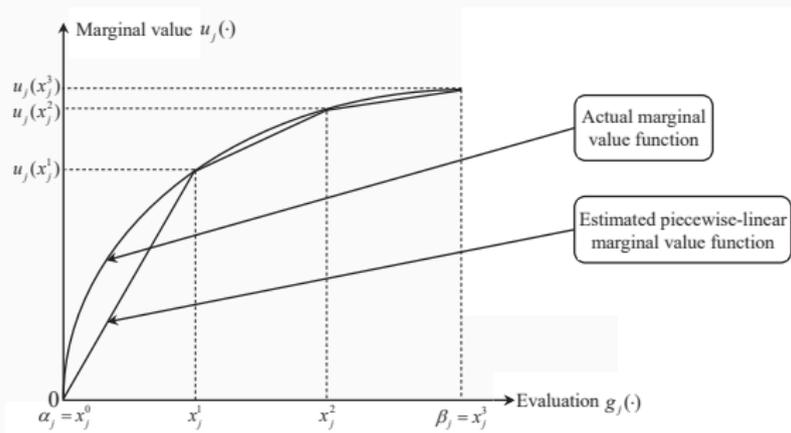
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To perform the assignment of alternative $a \in A \cup A^R$, we shall use as the preference model an additive value function U of the following form:

$$U(a) = \sum_{j=1}^n u_j(g_j(a)), \quad a \in A \cup A^R,$$

where $U(a)$ is the comprehensive value of a , and $u_j(g_j(a))$, $j = 1, \dots, n$, are marginal value functions for each criterion.

The proposed approach



- In this study, a piecewise-linear function $u_j(\cdot)$ is used to estimate the actual value function of criterion g_j , $j = 1, \dots, n$.

The proposed approach

- Defining the characteristic vector $\mathbf{V}(a) \in \mathbb{R}^\gamma$ of alternative a by

$$\mathbf{V}(a) = \left(\underbrace{v_1^1(a), \dots, v_1^{\gamma_1}(a)}_{\text{criterion } g_1}, \dots, \underbrace{v_j^1(a), \dots, v_j^{\gamma_j}(a)}_{\text{criterion } g_j}, \dots, \underbrace{v_n^1(a), \dots, v_n^{\gamma_n}(a)}_{\text{criterion } g_n} \right)^T$$

and denote

$$\mathbf{u} = \left(\underbrace{\Delta u_1^1, \dots, \Delta u_1^{\gamma_1}}_{\text{criterion } g_1}, \dots, \underbrace{\Delta u_j^1, \dots, \Delta u_j^{\gamma_j}}_{\text{criterion } g_j}, \dots, \underbrace{\Delta u_n^1, \dots, \Delta u_n^{\gamma_n}}_{\text{criterion } g_n} \right)^T,$$

we can compute comprehensive value $U(a)$ as follows:

$$U(a) = \mathbf{u}^T \mathbf{V}(a).$$

The proposed approach

The consistency principle for assignment: For any pair of alternatives a and b , a given value function $U(\cdot)$ is said to be consistent with the assignment of a and b (denoted by $C(a)$ and $C(b)$, respectively, and $C(a), C(b) \in \overline{C}$), if and only if

$$U(a) \geq U(b) \Rightarrow C(a) \succsim C(b), \quad (1)$$

$$U(a) \leq U(b) \Rightarrow C(a) \precsim C(b), \quad (2)$$

where \succsim and \precsim mean “as least as good as” and “as most as good as”, respectively. Observe that (1) and (2) are equivalent to

$$C(a) \prec C(b) \Rightarrow \mathbf{u}^T (\mathbf{V}(a) - \mathbf{V}(b)) < 0, \quad (3)$$

$$C(a) \succ C(b) \Rightarrow \mathbf{u}^T (\mathbf{V}(a) - \mathbf{V}(b)) > 0, \quad (4)$$

since $U(a) = \mathbf{u}^T \mathbf{V}(a)$ and $U(b) = \mathbf{u}^T \mathbf{V}(b)$.

The proposed approach

First, let us introduce a set of indicators $t(a^*, b^*)$ for any pair of reference alternatives $a^*, b^* \in A^R$ such that $C(a^*) \neq C(b^*)$, which are defined as

$$t(a^*, b^*) = \begin{cases} 1, & \text{if } C(a^*) \succ C(b^*), \\ 0, & \text{if } C(a^*) \prec C(b^*). \end{cases}$$

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According to the above consistency principle for assignment, we aim to find a vector \mathbf{u} such that, for any pair of reference alternatives $a^*, b^* \in A^R$ with $C(a^*) \neq C(b^*)$, we have

$$\mathbf{u}^T (\mathbf{V}(a^*) - \mathbf{V}(b^*)) \begin{cases} > 0, & \text{if } t(a^*, b^*) = 1, \\ < 0, & \text{if } t(a^*, b^*) = 0. \end{cases} \quad (5)$$

The proposed approach

Then, instead of using slack variables, we can transform $\mathbf{u}^T (\mathbf{V}(a^*) - \mathbf{V}(b^*))$ into a value $y(a^*, b^*)$ for any pair of reference alternatives $a^*, b^* \in A^R$ so that we can use the difference between $y(a^*, b^*)$ and $t(a^*, b^*)$ to measure the inconsistency. $y(a^*, b^*)$ should satisfy the following conditions:

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- (a) $y(a^*, b^*)$ is monotone and increasing with respect to $\mathbf{u}^T (\mathbf{V}(a^*) - \mathbf{V}(b^*))$,

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- (a) $y(a^*, b^*)$ is monotone and increasing with respect to $\mathbf{u}^T (\mathbf{V}(a^*) - \mathbf{V}(b^*))$,
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- (b) $y(a^*, b^*)$ is bounded within the interval $(0, 1)$,
- (c)
$$\begin{cases} 0 < y(a^*, b^*) < 0.5, & \text{if } \mathbf{u}^T (\mathbf{V}(a^*) - \mathbf{V}(b^*)) < 0, \\ y(a^*, b^*) = 0.5, & \text{if } \mathbf{u}^T (\mathbf{V}(a^*) - \mathbf{V}(b^*)) = 0, \\ 0.5 < y(a^*, b^*) < 1, & \text{if } \mathbf{u}^T (\mathbf{V}(a^*) - \mathbf{V}(b^*)) > 0. \end{cases}$$

The proposed approach

In this study, we use the following Sigmoid function to instantiate the function $y(a^*, b^*)$:

$$y(a^*, b^*) = \frac{1}{1 + e^{-\mathbf{u}^T(\mathbf{v}(a^*) - \mathbf{v}(b^*))}}. \quad (6)$$

The Sigmoid function satisfies all the above requirements of the function $y(a^*, b^*)$.

The proposed approach

Then, we can consider the following non-linear optimization model to derive a value function that is as both consistent and robust as possible.

$$\begin{aligned} \max \quad & \prod_{a^*, b^* \in A^R \text{ with } C(a^*) \neq C(b^*)} \left[\frac{1}{1 + e^{-\mathbf{u}^\top (\mathbf{V}(a^*) - \mathbf{V}(b^*))}} \right]^{t(a^*, b^*)} \\ & \cdot \left[1 - \frac{1}{1 + e^{-\mathbf{u}^\top (\mathbf{V}(a^*) - \mathbf{V}(b^*))}} \right]^{1-t(a^*, b^*)} \\ \text{s.t.} \quad & \mathbf{u}^\top \mathbf{e} = 1, \mathbf{u} \geq \mathbf{0}. \end{aligned}$$

The proposed approach

- In order to solve the non-linear optimization model for a large-scale problem efficiently, we propose a new parallel implementation for the Zoutendijk's feasible direction method based on the MapReduce framework.

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- In order to solve the non-linear optimization model for a large-scale problem efficiently, we propose a new parallel implementation for the Zoutendijk's feasible direction method based on the MapReduce framework.
- The model can be reformulated as follows

$$\begin{aligned} \min f(\mathbf{u}) = & \sum_{a^*, b^* \in A^R \text{ with } C(a^*) \neq C(b^*)} [-t (a^*, b^*) \mathbf{u}^T (\mathbf{V}(a^*) - \mathbf{V}(b^*)) \\ & + \ln (1 + e^{\mathbf{u}^T (\mathbf{V}(a^*) - \mathbf{V}(b^*))})] \\ \text{s.t. } & \mathbf{u}^T \mathbf{e} = 1, \mathbf{u} \geq \mathbf{0}. \end{aligned}$$

The proposed approach

The Zoutendijk's feasible direction method

Input:

Initial feasible solution $\hat{\mathbf{u}} = (1/\gamma, \dots, 1/\gamma)^T$.

- 1: Determine Ω and $\bar{\Omega}$ according to the current feasible solution $\hat{\mathbf{u}}$.
- 2: Calculate $\nabla f(\hat{\mathbf{u}})$.
- 3: Solve the LP model and obtain the optimal solution \mathbf{d}^* .
- 4: **if** $\nabla f(\hat{\mathbf{u}})^T \mathbf{d}^* = 0$ **then**
- 5: Stop and $\hat{\mathbf{u}}$ is the global optimal solution.
- 6: **else**
- 7: Solve the model and obtain the optimal solution λ^* .
- 8: Update $\hat{\mathbf{u}} \leftarrow \hat{\mathbf{u}} + \lambda^* \mathbf{d}^*$.
- 9: Go to step 1.
- 10: **end if**

Output:

The optimal solution $\hat{\mathbf{u}}$.

The proposed approach

$$\begin{aligned} \min f(\mathbf{u}) = & \sum_{a^*, b^* \in A^R \text{ with } C(a^*) \neq C(b^*)} [-t(a^*, b^*) \mathbf{u}^T (\mathbf{V}(a^*) - \mathbf{V}(b^*)) \\ & + \ln(1 + e^{\mathbf{u}^T (\mathbf{V}(a^*) - \mathbf{V}(b^*))})] \\ \text{s.t. } & \mathbf{u}^T \mathbf{e} = 1, \mathbf{u} \geq \mathbf{0}. \end{aligned}$$

- Considering that the number of reference alternatives in a large-scale problem is reasonably large, the objective is composed of a huge number of terms (i.e., $-t(a^*, b^*) \mathbf{u}^T (\mathbf{V}(a^*) - \mathbf{V}(b^*)) + \ln(1 + e^{\mathbf{u}^T (\mathbf{V}(a^*) - \mathbf{V}(b^*))})$, $a^*, b^* \in A^R$).
- This inspires us to utilize the MapReduce framework to accelerate the computation of $f(\mathbf{u})$ and $\nabla f(\mathbf{u})$ for the Zoutendijk's feasible direction method.

The proposed approach

Calculate $\nabla f(\hat{\mathbf{u}})$: Map phase.

Input:

$\langle \text{key}, \text{value} \rangle$ where *key* is the index of subset and *value* is the subset of pairs of reference alternatives $(a^*, b^*) \in A^R \times A^R$ such that $C(a^*) \neq C(b^*)$; the current feasible solution $\hat{\mathbf{u}}$.

- 1: $\rho \leftarrow \mathbf{0}$.
- 2: **for** any pair of reference alternatives (a^*, b^*) in this subset **do**
- 3: $\rho \leftarrow \rho + \left[-t(a^*, b^*) + \frac{e^{\hat{\mathbf{u}}^T(\mathbf{v}(a^*) - \mathbf{v}(b^*))}}{1 + e^{\hat{\mathbf{u}}^T(\mathbf{v}(a^*) - \mathbf{v}(b^*))}} \right] (\mathbf{V}(a^*) - \mathbf{V}(b^*))$.
- 4: **end for**

Output:

$\langle \text{key} = \hat{\mathbf{u}}, \text{value} = \rho \rangle$.

The proposed approach

Calculate $\nabla f(\hat{\mathbf{u}})$: Reduce phase.

Input:

$\langle \text{key} = \hat{\mathbf{u}}, \text{value} = \text{list}(\rho) \rangle$.

1: $\delta \leftarrow \mathbf{0}$.

2: **for** any ρ in $\text{list}(\rho)$ **do**

3: $\delta \leftarrow \delta + \rho$.

4: **end for**

Output:

$\langle \text{key} = \hat{\mathbf{u}}, \text{value} = \delta \rangle$ where δ is equal to $\nabla f(\hat{\mathbf{u}})$.

Experimental analysis

The experimental analysis is based on Best Chinese Universities Rankings (BCUR) in 2018, which provides the overall ranking of 600 universities in China.

Table 1: Considered criteria and corresponding indicators in BCUR.

Dimension	Criteria	Indicator
Teaching and learning	(g ₁) Quality of incoming students	Average score of incoming freshmen in national college entrance exam
	(g ₂) Education outcome	Employment rate of bachelor degree recipients
	(g ₃) Reputation	Income from donations
Research	(g ₄) Scale of research	Number of papers in Scopus
	(g ₅) Quality of research	Field weighted citation impact
	(g ₆) Top research achievements	World top 1% most cited paper
	(g ₇) Top scholars	Chinese most cited researchers
Social service	(g ₈) Technology service	Research income from industry
	(g ₉) Technology transfer	Income from technology transfer
Internationalization	(g ₁₀) International student ratio	International students as a percentage of total students

Experimental analysis

- We divide all the 600 universities into five categories according to their total scores. Each category is composed of 120 universities and C_{I_5} and C_{I_1} are the best and worst categories, respectively.
- The performance of the proposed approach is compared with that of the classical UTADIS method through *cross-validation*.

Table 2: Accuracy of different methods for the problem of university classification.

Method	$\gamma_j = 1$	$\gamma_j = 2$	$\gamma_j = 3$	$\gamma_j = 4$	$\gamma_j = 5$
UTADIS	0.9050	0.8917	0.9033	0.9100	0.9083
Proposed approach	0.9246	0.9285	0.9462	0.9598	0.9514
t-test	0.0000*	0.0000*	0.0000*	0.0000*	0.0000*

Thank you!